

Solution to problem 3. (a) Let V be given and assume it is large. Define item 1 to have value $v_1 = V - 1$ and weight $w_1 = 1/V$. Define item 2 to have value $v_2 = V$ and weight $w_2 = V$. In an integral solution, to accumulate a total value of $\geq V$ one must choose item 2, so the cheapest way is to do so, where the total weight is V . On the other hand, in a fractional solution, we can fully pick item 1 and pick $1/V$ portion of item 2. This yields a total value of $(V - 1) + V \cdot 1/V = V$, meeting the threshold, while the total weight is $1/V + V \cdot 1/V = 1 + 1/V$. The ratio between V (integral optimal weight) against $1 + 1/V$ (fractional optimal) can be made arbitrarily large.

(b) We replace the constraints with

$$\sum_{i \notin S} \min(v_i, V - v(S))x_i \geq \max(V - v(S), 0) \quad \text{for all } S \subset \{1, \dots, k\}.$$

The advantage of doing this, in particular using $\min(v_i, V - v(S))$ on the LHS is to specifically prevent the unfavorable event in (a) from happening.

(c) With the updated constraints, setting $S = \emptyset$ gives $(V - 1)x_1 + Vx_2 \geq V$, and setting $S = \{1\}$ gives $x_2 \geq 1$. The other two subsets, $\{2\}$ and $\{1, 2\}$ do not yield any additional constraints. Based on these, the fractional and integer optimal solutions are identical as they both pick item 2 and nothing else. Here, the integrality gap reduces to 1.

(d) Let x be the fractional optimal of the enhanced LP and let $\tilde{x}_i = \min\{2x_i, 1\}$ as described. Clearly, this yields a feasible solution, since $\tilde{x}_i \geq x_i$, so

$$\min_{i \notin S} (v_i, V - v(S))\tilde{x}_i \geq \min_{i \notin S} \min(v_i, V - v(S))x_i \geq \max(V - v(S), 0).$$

Our goal is to construct integer-valued solutions $y^{(j)}$ that recovers \tilde{x} via a convex combination. We let \mathcal{L} denote the set of **large** items: those whose $x_i \geq 1/2$ so $\tilde{x}_i = 1$. It follows that all $y_i^{(j)} = 1$ for the integer-valued solutions can only take values 0 or 1.

More interesting is \mathcal{S} , the set of **small** items where $x_i < 1/2$ so $\tilde{x}_i < 1$. We let M be sufficiently large so $m\tilde{x}_i \in \mathbb{Z}$ for all small items i . This is doable since the \tilde{x}_i 's are assumed to be rational.

In short, we construct M integer-valued solutions, where given small item i , we choose item i in $M\tilde{x}_i$ integer-valued solutions and discard it in the rest, achieving an average of \tilde{x}_i . The round-robin approach goes as follows.

- Sort small items in decreasing values of v_i .
- Let the first $M\tilde{x}_1$ solutions include item 1. Then let the next $M\tilde{x}_2$ solutions include item 2. Whenever we reach the last solution, take everything modulo M and repeat, so it goes on forever, until we are done assigning all small items.

The power of round-robin on these sorted small items is that the distribution of weights is fairly uniform. Let $S \subset \{1, \dots, k\}$ be given.

Observe that if a solution z satisfies the constraint with respect to \mathcal{S} , then \tilde{z} that is set to equal z on \mathcal{S} and takes 1 on all items in \mathcal{L} satisfies any constraint S . To see this, write S^c as $(S^c \cap \mathcal{S}) \cup (S^c \cap \mathcal{L})$. Then, by

the feasibility of x (the fractional optimal for LP),

$$\begin{aligned} \sum_{i \notin \mathcal{S}} \min(v_i, V - v(\mathcal{S})) \tilde{z}_i &= \sum_{i \in \mathcal{S}^c \cap \mathcal{S}} \min(v_i, V - v(\mathcal{S})) \cdot z_i + \sum_{i \in \mathcal{S}^c \cap \mathcal{L}} \min(v_i, V - v(\mathcal{S})) \\ &\geq \max(V - v(\mathcal{S} \cup \mathcal{L}), 0) + \max(V - v(\mathcal{S} \cup \mathcal{S}), 0) \\ &\geq \max(V - v(\mathcal{S}), 0). \end{aligned} \quad (*)$$

Therefore, to ensure a solution is overall feasible, it suffices to check (i) that the solution picks everything from \mathcal{L} , and (ii) it satisfies the constraint specifically for \mathcal{S} . Our goal is to show that all solutions obtained via round robin satisfies this constraint. **While this is not an intended separation oracle for (b), it achieves the goal of verifying if a solution is feasible.**

Observe that by the nature of round robin, the number of items picked by each $y^{(j)}$ must be identical or differ by at most 1:

$$\max_{j \geq 1} |\{i \in \mathcal{S} : y_i^{(j)} = 1\}| - \min_{j \geq 1} |\{i \in \mathcal{S} : y_i^{(j)} = 1\}| \leq 1.$$

Define

$$v(y^{(j)}) = \sum_{i \in \mathcal{S}} \min(v_i, V - v(\mathcal{S})) \mathbf{1}[y_i^{(j)} = 1]$$

the “strengthened” total value of items chosen by $y^{(j)}$ among \mathcal{S} . Because items are sorted in decreasing order of value, we know the earlier solutions accumulate more values, so $v(y^{(j)}) \geq v(y^{(j+1)})$. Thus it suffices to consider the disparity between $y^{(1)}$ and $y^{(M)}$ (the last one).

By round robin, $y^{(1)}$ can contain at most 1 extra element than $y^{(M)}$, and we assume so. We pair the 2nd element chosen by $y^{(1)}$ with the *first* of $y^{(M)}$, and likewise, the i^{th} element of $y^{(1)}$ with the $(i-1)^{\text{th}}$ element of $y^{(M)}$. This way, we see that in each pair, the value of $y^{(1)}$ is in fact smaller than that of $y^{(M)}$, and so $v(y^{(1)}) - v(y^{(M)}) \leq$ the value of the first element chosen by $y^{(1)}$, namely, $\min(v_{\max}, V - v(\mathcal{S}))$ where $v_{\max} = \max\{v_i : i \in \mathcal{S}\}$ corresponds to the most valuable item in \mathcal{S} , which by construction is included in $y^{(1)}$. Certainly, $\min(v_{\max}, V - v(\mathcal{S})) \leq V - v(\mathcal{S}) \leq \max(V - v(\mathcal{S}), 0)$, so

$$\max_{j_1, j_2} |v(y^{(j_1)}) - v(y^{(j_2)})| \leq \max(V - v(\mathcal{S}), 0). \quad (**)$$

Now suppose one of these solutions $y^{(j)}$ is infeasible. In particular, by the characterization in (*), $y^{(j)}$ must have violated the constraint for \mathcal{S} , so $\sum_{i \notin \mathcal{S}} \min(v_i, V - v(\mathcal{S})) y_i^{(j)} < \max(V - v(\mathcal{S}), 0)$. By (**) this implies that all other solutions’ $v()$ values must also be bounded by 2 times the RHS. Summing them over,

$$\sum_{j=1}^M v(y^{(j)}) = \sum_{j=1}^M \sum_{i \in \mathcal{S}} \min(v_i, V - v(\mathcal{S})) y_i^{(j)} < 2M \max(V - v(\mathcal{S}), 0).$$

On the other hand, $\sum_{j=1}^M y_i^{(j)}$ is also $M \tilde{x}_i$ by definition. Using $2x_i = \tilde{x}_i$ on \mathcal{S} , we further have

$$2M \sum_{i \in \mathcal{S}} \min(v_i, V - v(\mathcal{S})) x_i = M \sum_{i \in \mathcal{S}} \min(v_i, V - v(\mathcal{S})) \tilde{x}_i < 2M \max(V - v(\mathcal{S}), 0).$$

We see that x fails to meet the constraint w.r.t. \mathcal{S} , contradiction!

Therefore, all $y^{(j)}$ are feasible on \mathcal{S} , and when combined with all items in \mathcal{L} , they become feasible solutions for the strengthened min-weight knapsack LP. We have shown $\tilde{x} = M^{-1} \sum_{j=1}^M y^{(j)} \leq 2x$, so \tilde{x} is indeed a 2-approximation, as claimed.

Solution to problem 4. (a) This follows directly from the embedding theorem and the fact that a composition of $\text{polylog}(n)$ with a $\mathcal{O}(\log(n))$ transformation is also $\text{polylog}(n)$.

(b) Let the root of the tree be r . We are interested in finding a subtree such that for all $i \in [k]$, there exists a vertex $v \in S_i$ that connects r to v . In the language of LP, this can be formulated as

$$\min \sum_{e \in E} w_e x_e \quad \text{subject to} \quad \begin{cases} \sum_{e \in \delta(S)} x_e \geq 1 & \text{for all } S \subset V \text{ where } r \in S \text{ and } S \cap S_i = \emptyset \text{ for some } i \\ 0 \leq x_e \leq 1 & \text{for all } e \in E. \end{cases}$$

In other words, any cut that completely separates r from some S_i need to have value of at least 1.

There are exponential number of constraints, so we use a separation oracle. For each $i \in [k]$, an imaginary sink t_i adjacent to all $v \in S_i$, with edge weights all set to 1. The min-cut from r to t_i is < 1 if and only if the original constraint corresponding to (r, S_i) is violated.

(c) Consider a deep tree with $2n + 1$ nodes and height h : one root r , two leaves u, v , and two disjoint paths of length n from $r \rightarrow u$ and $r \rightarrow v$. Let $S_1 = \{u, v\}$. An optimal solution would assign $x_e = 1/2$ for each edge, but a randomized algorithm rounding $\mathbb{P}(x_e \text{ chosen}) = x_e$ will only yield a feasible solution with probability $\leq (1/2)^{n-1}$, for a full path from r to u or v needs to be entirely selected.

(d) (i) Let the output of this rounding scheme be ALG. We first show that $\mathbb{P}(e \in \text{ALG}) = x_e$ in this matter still; the only difference is that the events of edges being selected are no longer independent: if e has ancestors v_k, \dots, v_1, r , then

$$\mathbb{P}(x_e \in \text{ALG}) = \frac{x_e}{x_{v_k}} \cdot \frac{x_{v_k}}{x_{v_{k-1}}} \cdot \dots \cdot \frac{x_{v_1}}{x_r} \cdot x_r = x_e.$$

Therefore, the expected cost of ALG = $\sum_{e \in E} c_e \mathbb{P}(e \in \text{ALG}) = \sum_{e \in E} c_e x_e =$ the optimal LP solution.

(ii) I am aware that the GKR paper on the Group Steiner Tree problem gives a detailed proof of this claim via Janson's inequality, but even after digesting their proof, I still believe this is far beyond the scope of our class. While I'd love to have extra credit, I'm not worthy of it. :)

(iii) We repeat the GKR rounding for a total of $\Theta(\text{poly}(h) \cdot \text{polylog}(n) \cdot \log k)$ times, and take their union and call it SOL. Then, with appropriate coefficients,

$$\begin{aligned} \mathbb{P}(\text{SOL is not feasible}) &\leq \left(1 - \frac{1}{\text{poly}(h)\text{polylog}(n)}\right)^{\Theta(\text{poly}(h)\text{polylog}(n)\log k)} \\ &\leq \exp\left(-\frac{\Theta(\text{poly}(h) \cdot \text{polylog}(n) \cdot \log k)}{\text{poly}(h) \cdot \text{polylog}(n)}\right) = e^{-\log k} = \frac{1}{k}. \end{aligned}$$

With probability $1 - 1/k$, our output is a feasible solution with approximation factor $\Theta(\text{poly}(h) \cdot \text{polylog}(n) \cdot \log k) = \text{polylog}(n)$, since $h, k \leq n$. Otherwise, with low probability, we can brute force compute the shortest path from r to each S_i and append them paths to the solution. Clearly, any such shortest path has cost bounded by OPT (of the GST problem), so the total weight added is $\leq k \cdot \text{OPT}$. With probability $1/k$ of this happening, we add 1 to our approximation factor, and we see that $\text{polylog}(n)$ is still preserved.