

MATH 425b Homework 13

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Definition

If $\varphi, \psi \in (\mathbb{R}^n)^*$, define an alternating bilinear map, the **wedge product**, $\varphi \wedge \psi$ from $\mathbb{R}^n \times \mathbb{R}^n$ to \mathbb{R} , by

$$(\varphi \wedge \psi)(v, w) := \varphi(v)\psi(w) - \varphi(w)\psi(v).$$

Problem 1

Show that

$$\{dx \wedge dy, dx \wedge dz, dy \wedge dz\}$$

is a basis for the vector space of alternating bilinear maps from $\mathbb{R}^3 \times \mathbb{R}^3$ to \mathbb{R} . *Strictly speaking, dx, dy , and dz are differential 1-forms defined on \mathbb{R}^3 so we should evaluate them at a point $p \in \mathbb{R}^3$, but their values are independent of p and it is standard to just write dx, dy , and dz .*

Proof. From HW12 we know that $dx(p) = e_1^*, dy(p) = e_2^*$, and $dz(p) = e_3^*$, regardless of choice of p . Thus it suffices to show that

$$\{e_1^* \wedge e_2^*, e_1^* \wedge e_3^*, e_2^* \wedge e_3^*\}$$

forms a basis. By definition these three are indeed bilinear and alternating, so it remains to check their linear independence and span. For linear independence, suppose for some $i < j$ we have

$$c_1(e_1^* \wedge e_2^*)(e_i, e_j) + c_2(e_1^* \wedge e_3^*)(e_i, e_j) + c_3(e_2^* \wedge e_3^*)(e_i, e_j) = 0.$$

Then,

$$\begin{aligned} 0 &= c_1(e_1^*(e_i)e_2^*(e_j) - e_1^*(e_j)e_2^*(e_i)) \\ &\quad + c_2(e_1^*(e_i)e_3^*(e_j) - e_1^*(e_j)e_3^*(e_i)) \\ &\quad + c_3(e_2^*(e_i)e_3^*(e_j) - e_2^*(e_j)e_3^*(e_i)) \\ &= c_1(\delta_{1,i}\delta_{2,j} - \delta_{1,j}\delta_{2,i}) + c_2(\delta_{1,i}\delta_{3,j} - \delta_{1,j}\delta_{3,i}) + c_3(\delta_{2,i}\delta_{3,j} - \delta_{2,j}\delta_{3,i}) \\ &= c_1 \text{ if } (i, j) = (1, 2), \quad c_2 \text{ if } (i, j) = (2, 3), \quad \text{and } c_3 \text{ if } (i, j) = (2, 3). \end{aligned}$$

Therefore, letting i, j vary, we see $c_1 = c_2 = c_3 = 0$, i.e., these three wedge products are linearly independent.

To show they span the entire space of alternating bilinear maps, let $\Phi : \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}$ be an arbitrary map with such property. We aim to find c_1, c_2, c_3 such that $\Phi = c_1(e_1^* \wedge e_2^*) + c_2(e_1^* \wedge e_3^*) + c_3(e_2^* \wedge e_3^*)$. In particular, adopting

the Kronecker delta notation from above,

$$\Phi(e_1, e_2) = c_1 \quad \Phi(e_1, e_3) = c_2 \quad \text{and} \quad \Phi(e_2, e_3) = c_3.$$

Therefore

$$\Phi = \Phi(e_1, e_2)(e_1^* \wedge e_2^*) + \Phi(e_1, e_3)(e_1^* \wedge e_3^*) + \Phi(e_2, e_3)(e_2^* \wedge e_3^*).$$

The alternating property of Φ guarantees that it agrees with our hypothesized linear combination on all $(e_i, e_j) \in \mathbb{R}^3 \times \mathbb{R}^3$, not just those with $i < j$. For $i > j$, take for example $(i, j) = (2, 1)$:

$$\Phi(e_2, e_1) = c_1(\delta_{1,2}\delta_{2,1} - \delta_{1,1}\delta_{2,2}) = -c_1.$$

For $i = j$, since Φ is alternating, we expect $\Phi(e_j, e_i) = \Phi(e_i, e_j) = -\Phi(e_j, e_i)$ so $\Phi(e_i, e_j) = 0$. Indeed,

$$c_1(e_{1,k}e_{2,k} - e_{1,k}e_{2,k}) + \dots = 0.$$

Therefore $\{e_1^* \wedge e_2^*, e_1^* \wedge e_3^*, e_2^* \wedge e_3^*\}$ spans $\text{Alt}_2(\mathbb{R}^3, \mathbb{R})$. □

Problem 2

For an element $\alpha = a_1e_1^* + a_2e_2^* + a_3e_3^*$ of $\mathbb{R}^3 = \text{Alt}_1(\mathbb{R}^3, \mathbb{R})$, define $\Phi(\alpha) \in \mathbb{R}^3$ to be the vector (a_1, a_2, a_3) or equivalently $a_1e_1 + a_2e_2 + a_3e_3$. Similarly, for an element

$$\alpha = a_{12}e_1^* \wedge e_2^* + a_{13}e_1^* \wedge e_3^* + a_{23}e_2^* \wedge e_3^*$$

of $\text{Alt}_2(\mathbb{R}^3, \mathbb{R})$, define $\Phi(\alpha) \in \mathbb{R}^3$ to be the vector $(a_{23}, -a_{13}, a_{12})$ or equivalently $a_{23}e_1 - a_{13}e_2 + a_{12}e_3$. (The minus sign would disappear if we used $e_3^* \wedge e_1^*$ rather than $e_1^* \wedge e_3^*$.)

Show that, for $\alpha, \beta \in (\mathbb{R}^3)^*$ we have

$$\Phi(\alpha \wedge \beta) = \Phi(\alpha) \times \Phi(\beta)$$

where \times denotes the usual cross product of vectors in \mathbb{R}^3 .

Proof. By definition of wedge products,

$$\begin{aligned} \alpha \wedge \beta &= (a_1e_1^* + a_2e_2^* + a_3e_3^*) \wedge (b_1e_1^* + b_2e_2^* + b_3e_3^*) \\ &= a_1b_1(e_1^* \wedge e_1^*) + a_1b_2(e_1^* \wedge e_2^*) + a_1b_3(e_1^* \wedge e_3^*) \\ &\quad + a_2b_1(e_2^* \wedge e_1^*) + a_2b_2(e_2^* \wedge e_2^*) + a_2b_3(e_2^* \wedge e_3^*) \\ &\quad + a_3b_1(e_3^* \wedge e_1^*) + a_3b_2(e_3^* \wedge e_2^*) + a_3b_3(e_3^* \wedge e_3^*) \\ &= (a_1b_2 - a_2b_1)(e_1^* \wedge e_2^*) + (a_1b_3 - a_3b_1)(e_1^* \wedge e_3^*) + (a_2b_3 - a_3b_2)(e_2^* \wedge e_3^*) \end{aligned}$$

so

$$\Phi(\alpha \wedge \beta) = (a_2b_3 - a_3b_2)e_1 - (a_1b_3 - a_3b_1)e_2 + (a_1b_2 - a_2b_1)e_3$$

which is exactly the cross product of $\Phi(\alpha) \times \Phi(\beta) = (a_1, a_2, a_3) \times (b_1, b_2, b_3)$. □

Problem 3

More generally, the abstract definition of wedge products will imply that if $\varphi_1, \dots, \varphi_k$ are in $(\mathbb{R}^n)^*$ then

$$\varphi_1 \wedge \dots \wedge \varphi_k = \sum_{\sigma \in S_k} (-1)^{\text{sgn}(\sigma)} \varphi_{\sigma(1)} \otimes \dots \otimes \varphi_{\sigma(k)}.$$

In particular, for $\varphi_1, \varphi_2, \varphi_3 \in (\mathbb{R}^3)^*$ we have

$$\begin{aligned} \varphi_1 \wedge \varphi_2 \wedge \varphi_3 &= \varphi_1 \otimes \varphi_2 \otimes \varphi_3 - \varphi_1 \otimes \varphi_3 \otimes \varphi_2 \\ &\quad + \varphi_2 \otimes \varphi_3 \otimes \varphi_1 - \varphi_2 \otimes \varphi_1 \otimes \varphi_3 \\ &\quad + \varphi_3 \otimes \varphi_1 \otimes \varphi_2 - \varphi_3 \otimes \varphi_2 \otimes \varphi_1. \end{aligned}$$

Show that $\{dx \wedge dy \wedge dz\}$ is a basis for $\text{Alt}_3(\mathbb{R}^3, \mathbb{R})$.

Proof. We first show that anything of form $\varphi_1 \wedge \varphi_2 \wedge \varphi_3$ is alternating:

$$\begin{aligned} (\varphi_1 \wedge \varphi_2 \wedge \varphi_3)(v_1, v_3, v_2) &= \varphi_1(v_1)\varphi_2(v_3)\varphi_3(v_2) - \varphi_1(v_1)\varphi_3(v_3)\varphi_2(v_2) \\ &\quad - \varphi_2(v_1)\varphi_3(v_3)\varphi_1(v_2) + \varphi_2(v_1)\varphi_1(v_3)\varphi_3(v_2) \\ &\quad - \varphi_3(v_1)\varphi_1(v_3)\varphi_2(v_2) + \varphi_3(v_1)\varphi_2(v_3)\varphi_1(v_2) \\ &= -\varphi_1(v_1)\varphi_2(v_2)\varphi_3(v_3) + \varphi_1(v_1)\varphi_3(v_2)\varphi_2(v_3) \\ &\quad - \varphi_2(v_1)\varphi_3(v_2)\varphi_1(v_3) + \varphi_2(v_1)\varphi_1(v_2)\varphi_3(v_3) \\ &\quad - \varphi_3(v_1)\varphi_1(v_2)\varphi_2(v_3) + \varphi_3(v_1)\varphi_2(v_2)\varphi_1(v_3) \\ &= -(\varphi_1 \wedge \varphi_2 \wedge \varphi_3)(v_1, v_2, v_3). \end{aligned}$$

The remaining cases (e.g. comparing above with input (v_1, v_3, v_2)) are similar and omitted. Since $dx(p) = e_1^*$ and likewise for the other two, we have

$$(dx \wedge dy \wedge dz)(e_1, e_2, e_3) = e_1^*(e_1)e_2^*(e_2)e_3^*(e_3) = 1,$$

so indeed this wedge product is nontrivial.

To show that $\{dx \wedge dy \wedge dz\}$ spans $\text{Alt}_3(\mathbb{R}^3, \mathbb{R})$, it suffices to check that the latter is one-dimensional. Indeed, this is true because any multilinear map in $\text{Alt}_3(\mathbb{R}^3, \mathbb{R})$ corresponds to taking the determinant of a 3×3 matrix: if $\varphi_1 = f_{1,1}dx + f_{1,2}dy + f_{1,3}dz$ and likewise for the other two functionals, then

$$\varphi_1 \wedge \varphi_2 \wedge \varphi_3 = \begin{vmatrix} f_{1,1} & f_{1,2} & f_{1,3} \\ f_{2,1} & f_{2,2} & f_{2,3} \\ f_{3,1} & f_{3,2} & f_{3,3} \end{vmatrix} dx \wedge dy \wedge dz.$$

Given that the matrix is fixed and the determinant unique, we see that $\text{Alt}_3(\mathbb{R}^3, \mathbb{R})$ is one-dimensional as any 3-form on \mathbb{R}^3 is simply of form $f dx \wedge dy \wedge dz$ where f is a function on \mathbb{R}^3 . \square

Problem 4

Prove that $d \circ d = 0$ for d acting on 0-forms and 1-forms on \mathbb{R}^3 .

Proof. For a 0-form f on \mathbb{R}^3 ,

$$df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \frac{\partial f}{\partial z} dz.$$

It follows that (assuming the order of mixed partials is interchangeable, which is indeed guaranteed by symmetry of $D^2 f$)

$$\begin{aligned} (d \circ d)f &= \frac{\partial^2 f}{\partial x^2} dx \wedge dx + \frac{\partial^2 f}{\partial x \partial y} dx \wedge dy + \frac{\partial^2 f}{\partial x \partial z} dx \wedge dz \\ &\quad + \frac{\partial^2 f}{\partial y \partial x} dy \wedge dx + \frac{\partial^2 f}{\partial y^2} dy \wedge dy + \frac{\partial^2 f}{\partial y \partial z} dy \wedge dz \\ &\quad + \frac{\partial^2 f}{\partial z \partial x} dz \wedge dx + \frac{\partial^2 f}{\partial z \partial y} dz \wedge dy + \frac{\partial^2 f}{\partial z^2} dz \wedge dz \\ &= \left[\frac{\partial^2 f}{\partial x \partial y} - \frac{\partial^2 f}{\partial y \partial x} \right] dx \wedge dy + \left[\frac{\partial^2 f}{\partial x \partial z} - \frac{\partial^2 f}{\partial z \partial x} \right] dx \wedge dz + \left[\frac{\partial^2 f}{\partial y \partial z} - \frac{\partial^2 f}{\partial z \partial y} \right] dy \wedge dz = 0. \end{aligned}$$

Likewise, for any 1-form $\alpha := f dx + g dy + h dz$ on \mathbb{R}^3 ,

$$\begin{aligned} d\alpha &= \left[\frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \frac{\partial f}{\partial z} dz \right] \wedge dx \\ &\quad + \left[\frac{\partial g}{\partial x} dx + \frac{\partial g}{\partial y} dy + \frac{\partial g}{\partial z} dz \right] \wedge dy \\ &\quad + \left[\frac{\partial h}{\partial x} dx + \frac{\partial h}{\partial y} dy + \frac{\partial h}{\partial z} dz \right] \wedge dz \\ &= \left[\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right] dx \wedge dy + \left[\frac{\partial h}{\partial y} - \frac{\partial g}{\partial z} \right] dy \wedge dz + \left[\frac{\partial f}{\partial z} - \frac{\partial h}{\partial x} \right] dz \wedge dx, \end{aligned}$$

so taking the exterior derivative once more gives

$$\begin{aligned} (d \circ d)\alpha &= \left[\frac{\partial^2 g}{\partial x \partial z} - \frac{\partial^2 f}{\partial y \partial z} \right] dx \wedge dy \wedge dz \\ &\quad + \left[\frac{\partial^2 h}{\partial y \partial x} - \frac{\partial^2 g}{\partial z \partial x} \right] dy \wedge dz \wedge dx \\ &\quad + \left[\frac{\partial^2 f}{\partial z \partial y} - \frac{\partial^2 h}{\partial x \partial y} \right] dz \wedge dx \wedge dy \\ &= \left[\frac{\partial^2 g}{\partial x \partial z} - \frac{\partial^2 g}{\partial z \partial x} - \frac{\partial^2 f}{\partial y \partial z} + \frac{\partial^2 f}{\partial z \partial y} + \frac{\partial^2 h}{\partial y \partial x} - \frac{\partial^2 h}{\partial x \partial y} \right] dx \wedge dy \wedge dz \\ &= 0. \end{aligned}$$

Note that (x, y, z) , (y, z, x) , and (z, x, y) are all even permutations in S_3 and thus the signs agree. □

Problem 5

Let α be a 1-form on \mathbb{R}^3 and let V be the corresponding vector field. Show that the 2-form $d\alpha$ corresponds to the vector field $\text{curl}(V)$. Similarly, let β be a 2-form on \mathbb{R}^3 and let W be the corresponding vector field. Show that the 3-form $d\beta$ corresponds to the function $\text{div}(W)$.

Proof. The first part directly follows from the previous problem, as the curl of the vector field $\langle f, g, h \rangle$ is precisely

$$\left\langle \frac{\partial h}{\partial y} - \frac{\partial g}{\partial z}, \frac{\partial f}{\partial z} - \frac{\partial h}{\partial x}, \frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right\rangle.$$

For the second part, suppose our 2-form looks like $f dy \wedge dz + g dz \wedge dx + h dx \wedge dy$ (so that it represents the vector field $\langle f, g, h \rangle$). Then, its exterior derivative is

$$\begin{aligned} d\beta &= \left[\frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \frac{\partial f}{\partial z} dz \right] \wedge dy \wedge dz \\ &\quad + \left[\frac{\partial g}{\partial x} dx + \frac{\partial g}{\partial y} dy + \frac{\partial g}{\partial z} dz \right] \wedge dz \wedge dx \\ &\quad + \left[\frac{\partial h}{\partial x} dx + \frac{\partial h}{\partial y} dy + \frac{\partial h}{\partial z} dz \right] \wedge dx \wedge dy \\ &= \frac{\partial f}{\partial x} dx \wedge dy \wedge dz + \frac{\partial g}{\partial y} dy \wedge dz \wedge dx + \frac{\partial h}{\partial z} dz \wedge dx \wedge dy \\ &= \left(\frac{\partial f}{\partial x} + \frac{\partial g}{\partial y} + \frac{\partial h}{\partial z} \right) dx \wedge dy \wedge dz, \end{aligned}$$

which indeed corresponds to the divergence of $\langle f, g, h \rangle$. □